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An iterative regularization method for an abstract ill-posed biparabolic problem

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available at the end of the article**Abstract**

In this paper, we are concerned with the problem of approximating a solution of an ill-posed biparabolic problem in the abstract setting. In order to overcome the instability of the original problem, we propose a regularizing strategy based on the Kozlov-Maz'ya iteration method. Finally, some other convergence results including some explicit convergence rates are also established under *a priori* bound assumptions on the exact solution.

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1 Formulation of the problem

Throughout this paper H denotes a complex separable Hilbert space endowed with the inner product $\langle \cdot, \cdot \rangle$ and the norm $\| \cdot \|$, $\mathcal{L}(H)$ stands for the Banach algebra of bounded linear operators on H .

Let $A : \mathcal{D}(A) \subset H \rightarrow H$ be a positive, self-adjoint operator with compact resolvent, so that A has an orthonormal basis of eigenvectors $(\phi_n) \subset H$ with real eigenvalues $(\lambda_n) \subset \mathbb{R}_+$, i.e.,

$$A\phi_n = \lambda_n\phi_n, \quad n \in \mathbb{N}^*, \quad \langle \phi_i, \phi_j \rangle = \delta_{ij} = \begin{cases} 1, & \text{if } i = j, \\ 0, & \text{if } i \neq j, \end{cases}$$

$$0 < \nu \leq \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots, \quad \lim_{n \rightarrow \infty} \lambda_n = \infty,$$

$$\forall h \in H, \quad h = \sum_{n=1}^{\infty} h_n \phi_n, \quad h_n = \langle h, \phi_n \rangle.$$

In this paper, we consider the inverse source problem of determining the unknown source term $u(0) = f$ and the temperature distribution $u(t)$ for $0 \leq t < T$, in the following biparabolic problem:

$$\begin{cases} \mathcal{B}^2 u = \left(\frac{d}{dt} + A\right)^2 u(t) = u''(t) + 2Au'(t) + A^2 u(t) = 0, & 0 < t < T, \\ u(T) = g, & u_t(0) = 0, \end{cases} \quad (1)$$

where $0 < T < \infty$ and f is a given H -valued function.

In [1, 2] Kozlov and Maz'ya proposed an alternating iterative method to solve boundary value problems for general strongly elliptic and formally self-adjoint systems. After that, the idea of this method has been successfully used for solving a various classes of ill-posed (elliptic, parabolic, and hyperbolic) problems; see, *e.g.*, [3–7].

In this work we extend this method to our ill-posed bipolarabolic problem. To the best of our knowledge, the literature devoted to this class of problems is quite scarce, except the paper [8]. The study of this case is caused not only by theoretical interest, but also by practical necessity.

It is well known that the classical heat equation does not accurately describe the conduction of heat [9, 10]. Numerous models have been proposed for better describing this phenomenon, among them, we can cite the bipolarabolic model proposed in [11] for a more adequate mathematical description of heat and diffusion processes than the classical heat equation. For a physical motivation and other models we refer the reader to [12–15].

2 Preliminaries and basic results

In this section we present the notation and the functional setting which will be used in this paper and prepare some material which will be used in our analysis.

2.1 Notation

We denote by $\mathcal{C}(H)$ the set of all closed linear operators densely defined in H . The domain, range, and kernel of a linear operator $B \in \mathcal{C}(H)$ are denoted as $\mathcal{D}(B)$, $R(B)$, and $N(B)$; the symbols $\rho(B)$, $\sigma(B)$, and $\sigma_p(B)$ are used for the resolvent set, spectrum, and point spectrum of B , respectively. If V is a closed subspace of H , we denote by Π_V the orthogonal projection from H to V .

For ease of reading, we summarize some well-known facts for non-expansive operators.

Definition 2.1 A linear operator $M \in \mathcal{L}(H)$ is called non-expansive if

$$\|M\| \leq 1.$$

Theorem 2.1 ([16], Theorem 2.2) *Let $M \in \mathcal{L}(H)$ be a positive, self-adjoint operator with $\|M\| \leq 1$. Putting $V_0 = N(M)$ and $V_1 = N(I - M)$. Then we have*

$$s\text{-}\lim_{n \rightarrow +\infty} M^n = \Pi_{V_1}, \quad s\text{-}\lim_{n \rightarrow +\infty} (I - M)^n = \Pi_{V_0}$$

i.e.,

$$\forall h \in H, \quad \lim_{n \rightarrow +\infty} M^n h = \Pi_{V_1} h, \quad \lim_{n \rightarrow +\infty} (I - M)^n h = \Pi_{V_0} h.$$

For more details of the theory of non-expansive operators, we refer to Krasnosel'skii *et al.* [17], p.66.

Let us consider the operator equation

$$S\varphi = (I - M)\varphi = \psi \tag{2}$$

for non-expansive operators M .

Theorem 2.2 *Let M be a linear self-adjoint, positive, and non-expansive operator on H . Let $\hat{\psi} \in H$ be such that (2) has a solution $\hat{\phi}$. If 1 is not eigenvalue of M , i.e., $(I - M)$ is injective ($V_1 = N(I - M) = \{0\}$), then the successive approximations*

$$\varphi_{n+1} = M\varphi_n + \hat{\psi}, \quad n = 0, 1, 2, \dots,$$

converge to $\hat{\phi}$ for any initial data $\varphi_0 \in H$.

Proof From the hypothesis and by virtue of Theorem 2.1, we have

$$\forall \varphi_0 \in H, \quad M^n \varphi_0 \longrightarrow \Pi_{V_1} \varphi_0 = \Pi_{\{0\}} \varphi_0 = 0. \quad (3)$$

By induction with respect to n , it is easily seen that φ_n has the explicit form

$$\begin{aligned} \varphi_n &= M^n \varphi_0 + \sum_{j=0}^{n-1} M^j \hat{\psi} \\ &= M^n \varphi_0 + (I - M^n)(I - M)^{-1} \hat{\psi} \\ &= M^n \varphi_0 + (I - M^n) \hat{\phi}, \end{aligned}$$

and (3) allows us to conclude that

$$\hat{\phi} - \varphi_n = M^n(\varphi_0 - \hat{\phi}) \longrightarrow 0, \quad n \longrightarrow \infty. \quad (4)$$

□

Remark 2.1 In many situations, some boundary value problems for partial differential equations which are ill-posed can be reduced to Fredholm operator equations of the first kind of the form $B\varphi = \psi$, where B is compact, positive, and self-adjoint operator in a Hilbert space H . This equation can be rewritten in the following way:

$$\varphi = (I - \omega B)\varphi + \omega\psi = L\varphi + \omega\psi,$$

where $L = (I - \omega B)$, and ω is a positive parameter satisfying $\omega < \frac{1}{\|B\|}$. It is easily seen that the operator L is non-expansive and 1 is not eigenvalue of L . It follows from Theorem 2.2 that the sequence $\{\varphi_n\}_{n=0}^{\infty}$ converges and $(I - \omega B)^n \zeta \longrightarrow 0$, for every $\zeta \in H$ as $n \longrightarrow \infty$.

3 Ill-posedness of the problem and a conditional stability result

Let us consider the following well-posed problem:

$$\begin{cases} \mathcal{B}^2 w = \left(\frac{d}{dt} + A\right)^2 w(t) = w''(t) + 2Aw'(t) + A^2 w(t) = 0, & 0 < t < T, \\ w(0) = \xi, & w_t(0) = 0, \end{cases} \quad (5)$$

where $\xi \in \mathcal{D}(A)$.

Let us denote $\mathbb{H}^1 = \mathcal{D}(A) \times H$. Denoting $U = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ we define the norm in \mathbb{H}^1 as $\|U\|_{\mathbb{H}^1}^2 = \|Au_1\|^2 + \|u_2\|^2$. In this setting, the second-order differential equation (5) may be restated as a first-order system in the Hilbert space \mathbb{H}^1 as follows:

$$W'(t) = \mathcal{A}W(t), \quad W(0) = \begin{pmatrix} \xi \\ 0 \end{pmatrix}, \quad (6)$$

by setting

$$W(t) = \begin{pmatrix} w_1(t) \\ w_2(t) \end{pmatrix} = \begin{pmatrix} w(t) \\ w'(t) \end{pmatrix}, \quad \mathcal{A} = \begin{pmatrix} 0 & I \\ -A^2 & -2A \end{pmatrix},$$

where \mathcal{A} is linear unbounded operator with domain $\mathcal{D}(\mathcal{A}) = \mathcal{D}(A^2) \times \mathcal{D}(A)$.

It is well known that \mathcal{A} is a generator of a strongly continuous semigroup $\{\mathcal{T}(t) = e^{t\mathcal{A}}\}_{t \geq 0}$ on \mathbb{H}^1 ([18], Theorem 2.1), more precisely, $\mathcal{T}(t)$ is analytic with the following explicit form:

$$\mathcal{T}(t)Z = e^{t\mathcal{A}} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \sum_{n=1}^{\infty} e^{tB_n} \begin{pmatrix} \langle z_1, \phi_n \rangle \phi_n \\ \langle z_2, \phi_n \rangle \phi_n \end{pmatrix}, \quad Z = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \in \mathbb{H}^1, \quad (7)$$

where $B_n = \begin{pmatrix} 0 & 1 \\ -\lambda_n^2 & -2\lambda_n \end{pmatrix}$. By using some techniques of matrix algebra, we can give the form of e^{tB_n} as follows:

$$e^{tB_n} = \begin{pmatrix} e^{-\lambda_n t} + \lambda_n t e^{-\lambda_n t} & t e^{-\lambda_n t} \\ -\lambda_n^2 t e^{-\lambda_n t} & -\lambda_n t e^{-\lambda_n t} + e^{-\lambda_n t} \end{pmatrix}.$$

It follows that

$$\mathcal{T}(t)Z = \sum_{n=1}^{\infty} \begin{pmatrix} e^{-\lambda_n t} + \lambda_n t e^{-\lambda_n t} & t e^{-\lambda_n t} \\ -\lambda_n^2 t e^{-\lambda_n t} & -\lambda_n t e^{-\lambda_n t} + e^{-\lambda_n t} \end{pmatrix} \begin{pmatrix} \langle z_1, \phi_n \rangle \phi_n \\ \langle z_2, \phi_n \rangle \phi_n \end{pmatrix}. \quad (8)$$

By using semigroup theory [19], we show the existence and uniqueness of mild solution of the problem (6).

Theorem 3.1 *For any $W(0) \in \mathbb{H}^1$, problem (6) admits an unique solution $W \in C^1([0, +\infty[; \mathbb{H}^1) \cap \mathcal{C}([0, +\infty[; \mathbb{H}^1) \cap \mathcal{C}([0, +\infty[; \mathcal{D}(\mathcal{A}))$, given by*

$$W(t) = \mathcal{T}(t)W(0) = \sum_{n=1}^{\infty} \begin{pmatrix} e^{-\lambda_n t} + \lambda_n t e^{-\lambda_n t} & t e^{-\lambda_n t} \\ -\lambda_n^2 t e^{-\lambda_n t} & -\lambda_n t e^{-\lambda_n t} + e^{-\lambda_n t} \end{pmatrix} \begin{pmatrix} \langle z_1, \phi_n \rangle \phi_n \\ \langle z_2, \phi_n \rangle \phi_n \end{pmatrix}. \quad (9)$$

In particular, for $W(0) = \begin{pmatrix} \xi \\ 0 \end{pmatrix}$ we have

$$W(t) = \mathcal{T}(t)W(0) = \sum_{n=1}^{\infty} \begin{pmatrix} e^{-\lambda_n t} + \lambda_n t e^{-\lambda_n t} & t e^{-\lambda_n t} \\ -\lambda_n^2 t e^{-\lambda_n t} & -\lambda_n t e^{-\lambda_n t} + e^{-\lambda_n t} \end{pmatrix} \begin{pmatrix} \langle \xi, \phi_n \rangle \phi_n \\ 0 \end{pmatrix}. \quad (10)$$

As a consequence of Theorem 3.1, we have the following result.

Corollary 3.1 *For any $\xi \in \mathcal{D}(A)$, problem (5) admits an unique solution*

$$w \in C^2([0, +\infty[; H) \cap C^1([0, +\infty[; H) \cap \mathcal{C}([0, +\infty[; \mathcal{D}(A)) \\ \cap C^1([0, +\infty[; \mathcal{D}(A)) \cap C^2([0, +\infty[; \mathcal{D}(A^2))$$

given by

$$w(t) = \mathcal{R}(t; A)\xi = (I + tA)e^{-tA}\xi = \sum_{n=1}^{\infty} (1 + t\lambda_n)e^{-t\lambda_n} \langle \xi, \phi_n \rangle \phi_n. \quad (11)$$

Remark 3.1 It is easy to check that

$$\|\mathcal{R}(t; A)\| = \sup_{\lambda \geq \lambda_1} (1 + t\lambda)e^{-t\lambda} \leq (1 + t\lambda_1)e^{-t\lambda_1}, \quad (12)$$

$$\sup_{0 \leq t \leq T} \|\mathcal{R}(t; A)\| = \sup_{0 \leq t \leq T} (1 + t\lambda_1)e^{-t\lambda_1} = 1. \quad (13)$$

3.1 Ill-posedness of the problem (1)

Theorem 3.2 Let $g \in H$, then the unique formal solution of the problem (1) is given by

$$u(t) = \sum_{n=1}^{\infty} \left(\frac{1 + t\lambda_n}{1 + T\lambda_n} \right) e^{(T-t)\lambda_n} \langle g, \phi_n \rangle \phi_n. \quad (14)$$

In this case,

$$f = u(0) = \sum_{n=1}^{\infty} \frac{1}{1 + T\lambda_n} e^{T\lambda_n} \langle g, \phi_n \rangle \phi_n. \quad (15)$$

Proof By using the generalized Fourier method of expansion, the solution of (1) can be written formally in the form

$$u(t) = \sum_{n=1}^{\infty} u_n(t) \phi_n, \quad u_n = \langle u, \phi_n \rangle, \quad (16)$$

where $u_n(t) = \langle u(t), \phi_n \rangle$ is the Fourier coefficient of $u(t)$.

Substituting $u(T) = g = \sum_{n=1}^{\infty} g_n \phi_n$ and (16) into (1), we get the family of second-order ordinary differential equations

$$\begin{cases} u_n''(t) + 2\lambda_n u_n'(t) + \lambda_n^2 u_n = 0, & 0 < t < T, \\ u_n(T) = g_n, & u_n'(0) = 0. \end{cases} \quad (17)$$

For each fixed n , this differential equation is uniquely solvable and its unique solution is given by

$$u_n(t) = \left(\frac{1 + t\lambda_n}{1 + T\lambda_n} \right) e^{(T-t)\lambda_n} g_n = \sigma(t, \lambda_n) g_n.$$

Finally, the formal solution of the problem (1) takes the form

$$u(t) = \sum_{n=1}^{\infty} \left(\frac{1 + t\lambda_n}{1 + T\lambda_n} \right) e^{(T-t)\lambda_n} g_n \phi_n, \quad g_n = \langle g, \phi_n \rangle. \quad \square$$

From this representation we see that $u(t)$ is unstable in $[0, T[$. This follows from the high-frequency limit:

$$\sigma(t, \lambda_n) = \left(\frac{1 + t\lambda_n}{1 + T\lambda_n} \right) e^{(T-t)\lambda_n} \longrightarrow +\infty, \quad n \longrightarrow +\infty.$$

Remark 3.2 • In the classical backward parabolic problem

$$v_t + Av = 0, \quad 0 < t < T, \quad v(T) = g, \quad (18)$$

the unique formal solution is given by

$$v(t) = \sum_{n=1}^{\infty} \theta_n(t, \lambda_n) \langle g, \varphi_n \rangle \varphi_n, \quad (19)$$

where

$$\theta_n(t, \lambda_n) = e^{(T-t)\lambda_n} \longrightarrow +\infty, \quad n \longrightarrow +\infty.$$

In this case, the high-frequency $\theta_n(t, \lambda_n)$ are equal to $e^{(T-t)\lambda_n}$ and the problem is severely ill-posed.

- In the case of the biparabolic model, we have $\sigma_n = r_n \theta_n$, where

$$r_n = \left(\frac{1 + t\lambda_n}{1 + T\lambda_n} \right)$$

is the *relaxation coefficient* resulting from the *hyperbolic character* of the biparabolic model.

Observe that

$$\frac{t}{T} \leq r_n \leq \frac{1 + t\lambda_1}{1 + T\lambda_1} \leq 1 \quad (20)$$

and

$$u(t) = R(t)v(t), \quad (21)$$

where

$$\|R(t)\| = \sup_n \{r_n\} = r_1 = \frac{1 + t\lambda_1}{1 + T\lambda_1}. \quad (22)$$

From this remark, we observe that the degree of ill-posedness in the biparabolic model is relaxed compared to the classical parabolic case.

3.2 Conditional stability estimate

We would like to have estimates of the form

$$\|u(t)\| \leq \Psi(\|g\|),$$

for some function $\Psi(\cdot)$ which satisfies the condition $\Psi(s) \longrightarrow 0$ as $s \longrightarrow 0$.

Since the problem of determining $u(t)$ from the knowledge of $\{u(T) = g, u'(0) = 0\}$ is ill-posed, an estimate such as the above will not be possible unless we restrict the solution $u(t)$ to a certain source set $\mathcal{M} \subset H$.

In our model, we will see that we can employ the method of logarithmic convexity to identify this source set:

$$M_\rho = \{w(t) \in H : w \text{ obeys (1) and } \|Aw(0)\| \leq \rho < \infty\}. \quad (23)$$

We recall the following useful result (see, e.g., [12], p.19, [20], p.375).

Theorem 3.3 *Let $v(t)$ be the solution of problem (18). Then the following estimate holds:*

$$\forall t \in [0, T], \quad \|v(t)\| \leq \|v(T)\|^{\frac{t}{T}} \|v(0)\|^{\frac{T-t}{T}}. \quad (24)$$

Now, if we assume that $u(0) = f = \sum_{n=1}^{\infty} f_n \phi_n$ such that $\|Au(0)\| = \sum_{n=1}^{\infty} \lambda_n^2 |f_n|^2 \leq \infty$, then we have

$$\|TAu(0)\|^2 = T^2 \sum_{n=1}^{\infty} \lambda_n^2 |f_n|^2 \leq \sum_{n=1}^{\infty} (1 + T\lambda_n)^2 |f_n|^2 = \|(I + TA)u(0)\|^2$$

and

$$\|(I + TA)u(0)\|^2 = \sum_{n=1}^{\infty} \left(\left(\frac{1 + T\lambda_n}{\lambda_n} \right) \lambda_n \right)^2 |f_n|^2 \leq \left(\frac{1 + T\lambda_1}{\lambda_1} \right)^2 \sum_{n=1}^{\infty} \lambda_n^2 |f_n|^2,$$

which implies that

$$T\|Au(0)\| \leq \|(I + TA)u(0)\| \leq \left(\frac{1 + T\lambda_1}{\lambda_1} \right) \|Au(0)\|. \quad (25)$$

By virtue of the estimate (24) and the formulas

$$v(t) = \exp((T - t)A)g = \sum_{n=1}^{\infty} e^{(T-t)\lambda_n} g_n \phi_n,$$

$$u(t) = R(t)v(t) = (I + tA)(I + TA)^{-1}v(t)$$

$$= \sum_{n=1}^{\infty} \left(\frac{1 + t\lambda_n}{1 + T\lambda_n} \right) e^{(T-t)\lambda_n} g_n \phi_n$$

$$= \sum_{n=1}^{\infty} r_n e^{(T-t)\lambda_n} g_n \phi_n,$$

and

$$v(0) = (I + TA)u(0), \quad v(T) = u(T) = g,$$

we can write

$$\begin{aligned} \|u(t)\| &\leq \|R(t)\| \|v(t)\| \leq \|R(t)\| \left(\|v(0)\|^{\frac{T-t}{T}} \|v(T)\|^{\frac{t}{T}} \right) \\ &\leq \|R(t)\| \left(\|(I + TA)u(0)\|^{\frac{T-t}{T}} \|g\|^{\frac{t}{T}} \right). \end{aligned} \quad (26)$$

Combining (26) and (22), we derive the following estimate:

$$\|u(t)\| \leq C(t, T, \lambda_1) \left\{ \|Au(0)\|^{\frac{T-t}{T}} \|g\|^{\frac{t}{T}} \right\}, \quad (27)$$

where

$$C(t, T, \lambda_1) = \left(\frac{1 + t\lambda_1}{1 + T\lambda_1} \right) \left(\frac{1 + T\lambda_1}{\lambda_1} \right)^{\frac{T-t}{T}} \leq \left(\frac{1 + T\lambda_1}{\lambda_1} \right)^{\frac{T-t}{T}} = \gamma.$$

On the basis $\{\phi_n\}$ we introduce the Hilbert scale $(H^s)_{s \in \mathbb{R}}$ (resp. $(\mathfrak{E}^s)_{s \in \mathbb{R}}$) induced by A as follows:

$$H^s = \mathcal{D}(A^s) = \left\{ h \in H : \|h\|_{H^s}^2 = \sum_{n=1}^{\infty} \lambda_n^{2s} |\langle h, \varphi_n \rangle|^2 < +\infty \right\},$$

$$\mathfrak{E}^s = \mathcal{D}(e^{sTA}) = \left\{ h \in H : \|h\|_{\mathfrak{E}^s}^2 = \sum_{n=1}^{\infty} e^{2Ts\lambda_n} |\langle h, \varphi_n \rangle|^2 < +\infty \right\}.$$

Remark 3.3 Observe that

$$\begin{aligned} \forall n \geq 1, \quad & \left(\frac{\lambda_1}{1 + T\lambda_n} \right) \leq \left(\frac{\lambda_n}{1 + T\lambda_n} \right) \\ \Rightarrow \quad & \frac{1}{1 + T\lambda_n} \leq \left(\frac{1}{\lambda_1} \right) \left(\frac{\lambda_n}{1 + T\lambda_n} \right) \\ \Rightarrow \quad & \|u(0)\|^2 = \sum_{n=1}^{\infty} \left(\frac{1}{1 + T\lambda_n} \right)^2 e^{2T\lambda_n} |g_n|^2 \leq \left(\frac{1}{\lambda_1} \right)^2 \|Au(0)\|^2; \end{aligned} \quad (28)$$

$$\begin{aligned} \forall n \geq 1, \quad & \left(\frac{\lambda_1}{1 + T\lambda_1} \right) \leq \left(\frac{\lambda_n}{1 + T\lambda_n} \right) \leq \frac{1}{T} \\ \Rightarrow \quad & \left(\frac{\lambda_1}{1 + T\lambda_1} \right)^2 \sum_{n=1}^{\infty} e^{2T\lambda_n} |g_n|^2 \leq \sum_{n=1}^{\infty} \left(\frac{\lambda_n}{1 + T\lambda_n} \right)^2 e^{2T\lambda_n} |g_n|^2 \\ & \leq \left(\frac{1}{T} \right)^2 \sum_{n=1}^{\infty} e^{2T\lambda_n} |g_n|^2. \end{aligned} \quad (29)$$

Then we deduce that

$$\|u(0)\| + \|Au(0)\| < \infty \iff \|Au(0)\| < \infty \iff \sum_{n=1}^{\infty} e^{2T\lambda_n} |g_n|^2 < \infty. \quad (30)$$

Theorem 3.4 Problem (1) is conditionally well-posed on the set

$$M = \{w(t) \in H : \|Aw(0)\| < \infty\}$$

if and only if

$$g \in \mathfrak{E}^1 = \left\{ h \in H : \sum_{n=1}^{\infty} e^{2T\lambda_n} |\langle h, \varphi_n \rangle|^2 < \infty \right\}.$$

Moreover, if $u(t) \in M_\rho$, then we have the Hölder continuity,

$$\|u(t)\| \leq \Psi(\|g\|) = \gamma(\rho^{\frac{T-t}{T}}) \|g\|^{\frac{t}{T}}. \quad (31)$$

4 Regularization by Kozlov-Maz'ya iteration method and error estimates

4.1 Description of the method

The iterative algorithm for solving the ill-posed problem (1) starts by letting $f_0 \in H$ be arbitrary. The first approximation $u^0(t)$ is the solution to the direct problem

$$\begin{cases} \mathcal{B}^2 u^0(t) = (\frac{d}{dt} + A)^2 u^0(t) = 0, & 0 < t \leq T, \\ u^0(0) = f_0, & u_t^0(0) = 0. \end{cases} \quad (32)$$

If the pair (u^k, f_k) has been constructed, let

$$(P)_{k+1}: \quad f_{k+1} = f_k - \omega(u^k(T) - g), \quad (33)$$

where ω is such that

$$0 < \omega < \omega^* = \frac{1}{\|K\|} = \frac{e^{T\lambda_1}}{(1 + T\lambda_1)},$$

where

$$\|K\| = \|\mathcal{R}(T, A)\| = \sup_{n \geq 1} \{(1 + T\lambda_n)e^{-T\lambda_n}\} = (1 + T\lambda_1)e^{-T\lambda_1},$$

and $\mathcal{R}(t, A)$ is the resolving operator associated to the direct well-posed biparabolic problem (5), given by the expression (11).

Finally, we get u^{k+1} by solving the problem

$$\begin{cases} \mathcal{B}^2 u^{k+1}(t) = (\frac{d}{dt} + A)^2 u^{k+1}(t) = 0, & 0 < t \leq T, \\ u^{k+1}(0) = f_{k+1}, & u_t^{k+1}(0) = 0. \end{cases} \quad (34)$$

We set $G = (I - \omega K)$. If we iterate backwards in $(P)_{k+1}$ we obtain

$$f_k = G^k f_0 + \omega \sum_{i=0}^{k-1} G^i f = G^k f_0 + (I - G^k)K^{-1}f = G^k f_0 + u(0) - G^k u(0). \quad (35)$$

This implies that

$$f_k - u(0) = G^k(f_0 - u(0)), \quad u^k(t) - u(t) = \mathcal{R}(t; A)G^k(f_0 - u(0)). \quad (36)$$

Proposition 4.1 *The operator $G = (I - \omega K)$ is self-adjoint and non-expansive on H . Moreover, it does not have 1 as eigenvalue.*

Proof The self-adjointness follows from the definition of G . Since we have the inequality $0 < 1 - \omega(1 + T\lambda)e^{-T\lambda} < 1$ for $\lambda \in \sigma(A)$, we have $\sigma_p(G) \subset]0, 1[$, then 1 is not eigenvalue of G . \square

Remark 4.1 Let $k \in \mathbb{N}^*$. Then we have

$$\|G\| = \|I - \omega K\| < 1 \implies \left\| \sum_{i=0}^{k-1} G^i \right\| \leq \sum_{i=0}^{k-1} \|G^i\| \leq k. \quad (37)$$

In general, the exact solution $u(0) = f \in H$ is required to satisfy a so-called source condition [21], otherwise the convergence of the regularization method approximating the problem can be arbitrarily slow. To accelerate the convergence of the regularization method, we assume the following source conditions:

$$(f_0 - u(0)) \in \mathcal{D}(A^{1+\beta}), \quad \beta > 0. \quad (38)$$

We provide the following lemma which will be used in the proof of convergence estimates.

Lemma 4.1 *Let $\sigma > 0$, $k \geq 2$, and Φ the real-valued function defined by*

$$\Phi(\lambda) = (1 - \omega(1 + T\lambda)e^{-T\lambda})^k \lambda^{-\sigma}, \quad \lambda \in [\lambda_1, \infty[, \quad (39)$$

where $\lambda_1 > 0$ and $\omega < \omega^* = \frac{1}{(1+T\lambda_1)e^{-T\lambda_1}}$. Then we have

$$\Phi_\infty = \sup_{\lambda \geq \lambda_1} \Phi(\lambda) \leq C \left(\frac{1}{\ln(k)} \right)^\sigma. \quad (40)$$

Proof We have

$$\Phi(\lambda) \leq \hat{\Phi}(\lambda) = (1 - \omega(1 + T\lambda_1)e^{-T\lambda})^k \lambda^{-\sigma}, \quad \lambda \in [\lambda_1, \infty[.$$

For notational convenience and simplicity, we denote

$$\begin{aligned} \mu &= T\lambda, & \tau &= \omega(1 + T\lambda_1), & \mu_1 &= T\lambda_1, \\ \hat{\Phi}(\lambda) &= (1 - \tau e^{-\mu})^k (T^{-1}\mu)^{-\sigma} = T^\sigma (1 - \tau e^{-\mu})^k \mu^{-\sigma} = T^\sigma \tilde{\Phi}(\mu), & \mu &\in [\mu_1, \infty[. \end{aligned}$$

The question now is to show that there exists a positive constant μ^* such that $\tilde{\Phi}(\mu) = (1 - \tau e^{-\mu})^k \mu^{-\sigma}$ is monotonically increasing in $[\mu_1, \mu^*]$ and monotonically decreasing in $]\mu^*, \infty[$. Since $\tilde{\Phi}(\mu)$ is continuously differentiable in $[\mu_1, \infty[$ and

$$\tilde{\Phi}(\mu_1) > 0, \quad \tilde{\Phi}(\infty) = 0, \quad \tilde{\Phi}(\mu) \geq 0,$$

then the maximum of $\tilde{\Phi}(\mu)$ is attained at an interior point, which is a critical point of $\tilde{\Phi}(\mu)$. From

$$\frac{d\tilde{\Phi}(\mu)}{d\mu} = \mu^{-\sigma-1} (1 - \tau e^{-\mu})^{k-1} \{ \tau(k\mu + \sigma)e^{-\mu} - \sigma \}$$

it follows that a critical point of $\tilde{\Phi}(\mu)$ in $]\mu_1, \infty[$ satisfies

$$\tau(k\mu + \sigma)e^{-\mu} - \sigma = 0 \quad \Longleftrightarrow \quad (k\mu + \sigma)e^{-\mu} - \frac{\sigma}{\tau} = 0.$$

We introduce the auxiliary function

$$D(\mu) = (k\mu + \sigma)e^{-\mu} - \frac{\sigma}{\tau}, \quad \mu \in [\mu_1, \infty[.$$

For k sufficiently large, $D(\mu^* = \ln(k)) = \frac{k \ln(k) + \sigma}{k} - \frac{\sigma}{\tau} > 0$. For $a > 1$ and k sufficiently large, we have $D(\mu^{**} = \ln(k^a)) = \frac{ak \ln(k) + \sigma}{k^a} - \frac{\sigma}{\tau} < 0$. Therefore, there exists $\hat{k}(a)$ such that

$$D(\ln(k)) > 0, \quad \forall k \geq \hat{k}(a),$$

$$D(\ln(k^a)) < 0, \quad \forall k \geq \hat{k}(a).$$

Consequently the critical point v of $D(\mu)$ must lie between $\mu^* = \ln(k)$ and $\mu^{**} = \ln(k^a)$, i.e., $v \in]\mu^*, \mu^{**}[$. Now let $k \geq \max(2, \hat{k}(a))$. Then we have

$$\sup_{\mu \in [\mu^*, +\infty[} \tilde{\Phi}(\mu) = \tilde{\Phi}(v) = (1 - \tau e^{-v})^k v^{-\sigma} \leq v^{-\sigma} \leq (\mu^*)^{-\sigma} = (\ln(k))^{-\sigma}.$$

Thus, the upper bound of $\Phi(\lambda)$ can be estimated as follows:

$$\sup_{\lambda \in [\lambda_1, +\infty[} \Phi(\lambda) \leq \sup_{\lambda \in [\lambda_1, +\infty[} \hat{\Phi}(\lambda) = T^\sigma \sup_{\mu \in [\mu^*, +\infty[} \tilde{\Phi}(\mu) \leq T^\sigma (\ln(k))^{-\sigma}. \quad \square$$

Now we are in a position to state the main result of this method.

Theorem 4.1 *Let $g \in \mathfrak{E}^1$ and ω satisfy $0 < \omega < \omega^*$, $f_0 \in H^1$, be an arbitrary element for the iterative procedure suggested above and u^k be the k th approximate solution. Then we have*

$$\sup_{t \in [0, T]} \|u(t) - u^k(t)\| \rightarrow 0, \quad k \rightarrow \infty. \quad (41)$$

Moreover, if $(f_0 - u(0)) \in H^\sigma$, $\sigma = \beta + 1$ ($\beta > 0$), i.e.,

$$\|f_0 - u(0)\|_{H^\sigma}^2 = \sum_{n=1}^{\infty} \lambda_n^{2\sigma} |\langle f - u(0), \phi_n \rangle|^2 \leq E^2,$$

then the rate of convergence of the method is given by

$$\sup_{t \in [0, T]} \|u(t) - u^k(t)\| \leq CE \left(\frac{1}{\ln(k)} \right)^{1+\beta}, \quad k \geq 2. \quad (42)$$

Proof By virtue of Proposition 4.1, Theorem 2.2, and the estimate (13), it follows immediately that

$$\begin{aligned} \sup_{t \in [0, T]} \|u(t) - u^k(t)\| &= \sup_{t \in [0, T]} \|\mathcal{R}(t; A) G^k(f_0 - u(0))\| \leq \sup_{t \in [0, T]} \|\mathcal{R}(t; A)\| \|G^k(f_0 - u(0))\| \\ &\leq \|G^k(f_0 - u(0))\| \rightarrow 0, \quad k \rightarrow \infty. \end{aligned}$$

We have

$$\begin{aligned} \|u(t) - u^k(t)\|^2 &= \|\mathcal{R}(t; A) G^k(f_0 - u(0))\|^2 \\ &\leq \|\mathcal{R}(t; A)\|^2 \|G^k(f_0 - u(0))\|^2 \leq \sum_{n=1}^{\infty} \Phi(\lambda_n)^2 \lambda_n^{2\sigma} |\langle f_0 - u(0), \phi_n \rangle|^2 \\ &\leq \left(\sup_n \Phi(\lambda_n) \right)^2 \|f_0 - u(0)\|_{H^\sigma}^2 \leq \left(\sup_n \Phi(\lambda_n) \right)^2 E^2, \end{aligned}$$

and by virtue of Lemma 4.1 (estimate (40)), we conclude the desired estimate. \square

Remark 4.2 Under the conditions $(f_0 - u(0)) \in H^\sigma$, $\sigma = 1 + \beta$, $\beta > 0$, and

$$\sup_{\lambda \geq \lambda_1} \{\lambda \Phi(\lambda)\} \leq C \left(\frac{1}{\ln(k)} \right)^\beta,$$

we can write

$$\|A(u(t) - u^k(t))\| \leq CE \left(\frac{1}{\ln(k)} \right)^\beta. \quad (43)$$

Proof

$$\begin{aligned} \|A(u(t) - u^k(t))\|^2 &= \|A\mathcal{R}(t; A)G^k(f_0 - u(0))\|^2 \\ &\leq \|\mathcal{R}(t; A)\|^2 \|AG^k(f_0 - u(0))\|^2 \\ &\leq \sum_{n=1}^{\infty} \{\lambda_n \Phi(\lambda_n)\}^2 \lambda_n^{2\sigma} |(f_0 - u(0), \phi_n)|^2 \\ &\leq \left(\sup_n \lambda_n \Phi(\lambda_n) \right)^2 \|f_0 - u(0)\|_{H^\sigma}^2 \\ &\leq \left(\sup_n \lambda_n \Phi(\lambda_n) \right)^2 E^2 \\ &\leq \left\{ CE \left(\frac{1}{\ln(k)} \right)^\beta \right\}^2. \end{aligned} \quad \square$$

Theorem 4.2 Let $g \in \mathfrak{E}^1$ and ω satisfy $0 < \omega < \omega^*$, and let $f_0 \in H^1$ be an arbitrary element for the iterative procedure suggested above and u^k (resp. u_k^δ) be the k th approximate solution for the exact data g (resp. for the inexact data g^δ) such that $\|g - g^\delta\| \leq \delta$. Then under the condition (38), the following inequality holds:

$$\sup_{t \in [0, T]} \|u(t) - u_k^\delta(t)\| \leq CE \left(\frac{1}{\ln(k)} \right)^{1+\beta} + \varepsilon(k)\delta,$$

where $\varepsilon(k) = \|\omega \sum_{i=0}^{k-1} (I - \omega K)^i\| \leq k\omega$.

Proof Using (35) and the triangle inequality, we can write

$$f^k = G^k f_0 + \omega \sum_{i=0}^{k-1} G^i g, \quad u_k(t) = \mathcal{R}(t; A)f^k, \quad (44)$$

$$f_\delta^k = G^k f_0 + \omega \sum_{i=0}^{k-1} G^i g^\delta, \quad u_k^\delta(t) = \mathcal{R}(t; A)f_\delta^k, \quad (45)$$

$$\|u(t) - u_k^\delta(t)\| = \|(u(t) - u^k(t)) + (u^k(t) - u_k^\delta(t))\| \leq \Delta_1 + \Delta_2,$$

where

$$\Delta_1 = \|u(t) - u^k(t)\| \leq \|u(t) - u^k(t)\|_\infty \leq CE \left(\frac{1}{\ln(k)} \right)^{1+\beta}, \quad k \geq 2, \quad (46)$$

and

$$\begin{aligned}\Delta_2 &= \|u^k(t) - u_\delta^k(t)\| = \|\mathcal{R}(t; A)(f^k - f_\delta^k)\| = \left\| \omega \mathcal{R}(t; A) \sum_{i=0}^{k-1} G^i (g - g^\delta) \right\| \\ &\leq \left\| \omega \sum_{i=0}^{k-1} G^i (g - g^\delta) \right\| \leq \left\| \omega \sum_{i=0}^{k-1} G^i \right\| \delta = \hat{\Delta}_2.\end{aligned}$$

By using inequality (37), the quantity $\hat{\Delta}_2$ can be estimated as follows:

$$\hat{\Delta}_2 \leq \omega k \delta. \quad (47)$$

Combining (46) and (47) and taking the supremum with respect to $t \in [0, T]$ of $\|u(t) - u_\delta^k(t)\|$, we obtain the desired bound. \square

Remark 4.3 Choosing $k = k(\delta)$ such that $\omega k \delta \rightarrow 0$ as $\delta \rightarrow 0$, we obtain

$$\sup_{t \in [0, T]} \|u^k(t) - u_\delta^k(t)\| \rightarrow 0 \quad \text{as } k \rightarrow +\infty.$$

5 Numerical results

In this section we give a two-dimensional numerical test to show the feasibility and efficiency of the proposed method. Numerical experiments were carried out using Matlab.

We consider the following inverse problem:

$$\begin{cases} (\frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2})^2 u(x, t) = 0, & x \in (0, \pi), t \in (0, 1), \\ u(0, t) = u(\pi, t) = 0, & t \in (0, 1), \\ u(x, 1) = g(x), & u_t(x, 0) = 0, \quad x \in [0, \pi], \end{cases} \quad (48)$$

where $f(x) = u(x, 0)$ is the unknown initial condition and $u(x, 1) = g(x)$ is the final condition.

It is easy to check that the operator

$$A = -\frac{\partial^2}{\partial x^2}, \quad \mathcal{D}(A) = H_0^1(0, \pi) \cap H^2(0, \pi) \subset H = L^2(0, \pi),$$

is positive, self-adjoint with compact resolvent (A is diagonalizable).

The eigenpairs (λ_n, ϕ_n) of A are

$$\lambda_n = n^2, \quad \phi_n(x) = \sqrt{\frac{2}{\pi}} \sin(nx), \quad n \in \mathbb{N}^*.$$

In this case, (15) takes the form

$$f(x) = u(x, 0) = \frac{2}{\pi} \sum_{n=1}^{+\infty} \frac{1}{1+n^2} e^{n^2} \left(\int_0^\pi g(x) \sin(nx) dx \right) \sin(nx). \quad (49)$$

In the following, we consider an example which has an exact expression of solutions $(u(x, t), f(x))$.

Example If $u(x, 0) = \phi_1(x) = \sqrt{\frac{2}{\pi}} \sin(x)$, then the function

$$u(x, t) = \sum_{n=1}^{\infty} (1 + t\lambda_n) e^{-t\lambda_n} \langle \phi_1, \phi_n \rangle \phi_n(x) = (1 + t\lambda_1) e^{-t\lambda_1} \phi_1(x) = \sqrt{\frac{2}{\pi}} (1 + t\lambda_1) e^{-t\lambda_1} \sin(x)$$

is the exact solution of the problem (48). Consequently, the data function is $g(x) = u(x, 1) = \sqrt{\frac{2}{\pi}} \frac{2}{e} \sin(x)$.

Kozlov-Maz'ya iteration method. By using the central difference with step length $h = \frac{\pi}{N+1}$ to approximate the first derivative u_x and the second derivative u_{xx} , we can get the following semi-discrete problem (ordinary differential equation):

$$\begin{cases} \left(\frac{d}{dt} - \mathbb{A}_h\right)^2 u(x_i, t) = 0, & x_i = ih, i = 1, \dots, N, t \in (0, 1), \\ u(x_0, t) = u(x_{N+1}, t) = \pi, & t \in (0, 1), \\ u(x_i, 0) = g(x_i), & u_t(x_i, 0) = 0, \quad x_i = ih, i = 1, \dots, N, \end{cases} \quad (50)$$

where \mathbb{A}_h is the discretization matrix stemming from the operator $A = -\frac{d^2}{dx^2}$:

$$\mathbb{A}_h = \frac{1}{h^2} \text{Tridiag}(-1, 2, -1) \in \mathcal{M}_N(\mathbb{R})$$

is a symmetric, positive definite matrix. We assume that it is fine enough so that the discretization errors are small compared to the uncertainty δ of the data; this means that \mathbb{A}_h is a good approximation of the differential operator $A = -\frac{d^2}{dx^2}$, whose unboundedness is reflected in a large norm of \mathbb{A}_h . The eigenpairs (μ_k, e_k) of \mathbb{A}_h are given by

$$\mu_k = 4 \left(\frac{N+1}{\pi} \right)^2 \sin^2 \left(\frac{k\pi}{2(N+1)} \right), \quad e_k = \left(\sin \left(\frac{jk\pi}{N+1} \right) \right)_{j=1}^N, \quad k = 1, \dots, N.$$

Adding a random distributed perturbation (obtained by the Matlab command `randn`) to each data function, we obtain the vector g^δ :

$$g^\delta = g + \varepsilon \text{randn}(\text{size}(g)),$$

where ε indicates the noise level of the measurement data and the function 'randn(\cdot)' generates arrays of random numbers whose elements are normally distributed with mean 0, variance $\sigma^2 = 1$, and standard deviation $\sigma = 1$. 'randn(size(g))' returns an array of random entries that is the same size as g . The bound on the measurement error δ can be measured in the sense of the root mean square error (RMSE) according to

$$\delta = \|g^\delta - g\|_* = \left(\frac{1}{N} \sum_{i=1}^N (g(x_i) - g^\delta(x_i))^2 \right)^{1/2}.$$

The discrete iterative approximation of (45) takes the form

$$f_k^\delta(x_j) = (I - \omega K_h)^k f_0(x_j) + \omega \sum_{i=0}^{k-1} (I - \omega K_h)^i g^\delta(x_j), \quad j = 1, \dots, N, \quad (51)$$

where $K_h = (I_N + \mathbb{A}_h) e^{-\mathbb{A}_h}$ and $\omega < \omega^* = \frac{1}{\|K_h\|} = \frac{e^{\mu_1}}{1 + \mu_1}$.

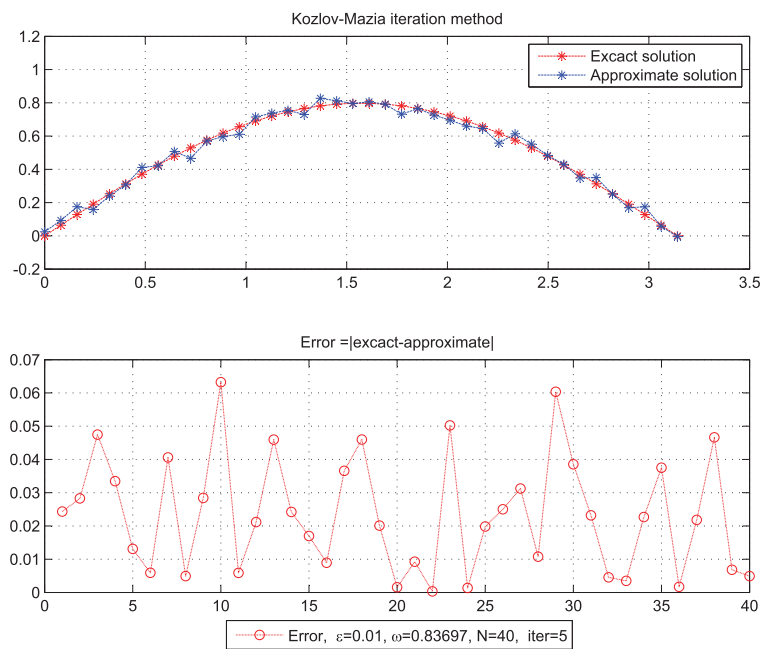


Figure 1 Noise level = 1/100, iter = 5.

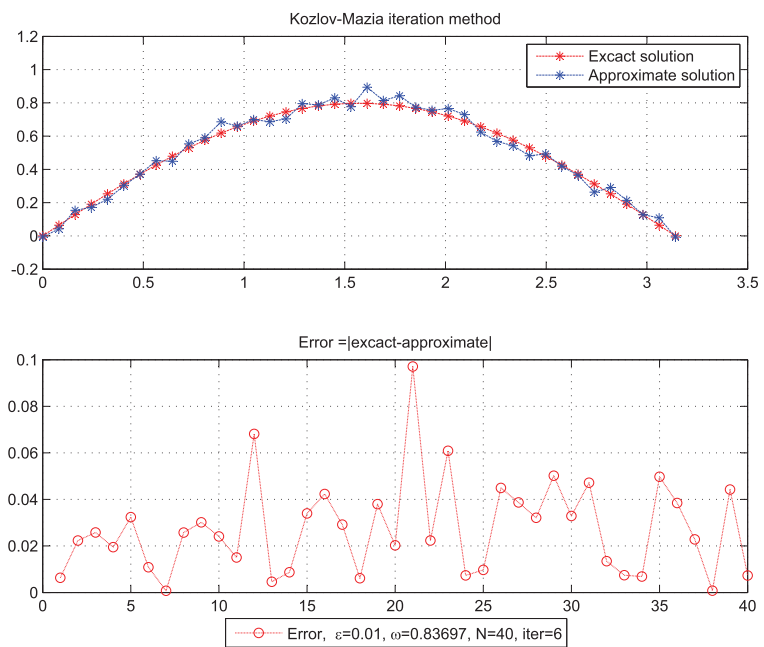


Figure 2 Noise level = 1/100, iter = 6.

Figures 1-4 show the comparison between the exact solution and its computed approximations for different values N ($:=$ number of grid points), k ($:=$ number of iterations), ω ($:=$ relaxation factor), ε ($:=$ noisy level) and $E_r(f) = \frac{\|f_{\text{approximate}} - f_{\text{exact}}\|_*}{\|f_{\text{exact}}\|_*}$ ($:=$ relative error).

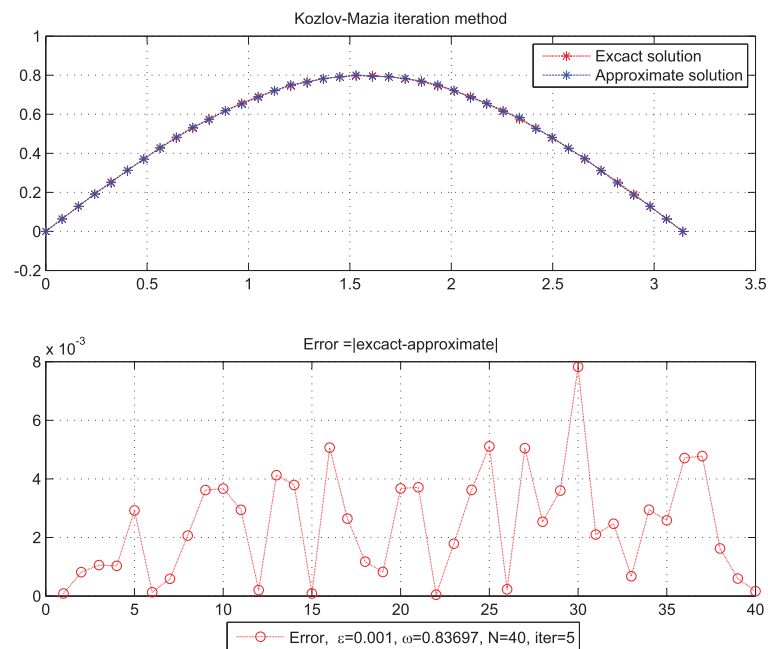


Figure 3 Noise level = 1/1,000, iter = 5.

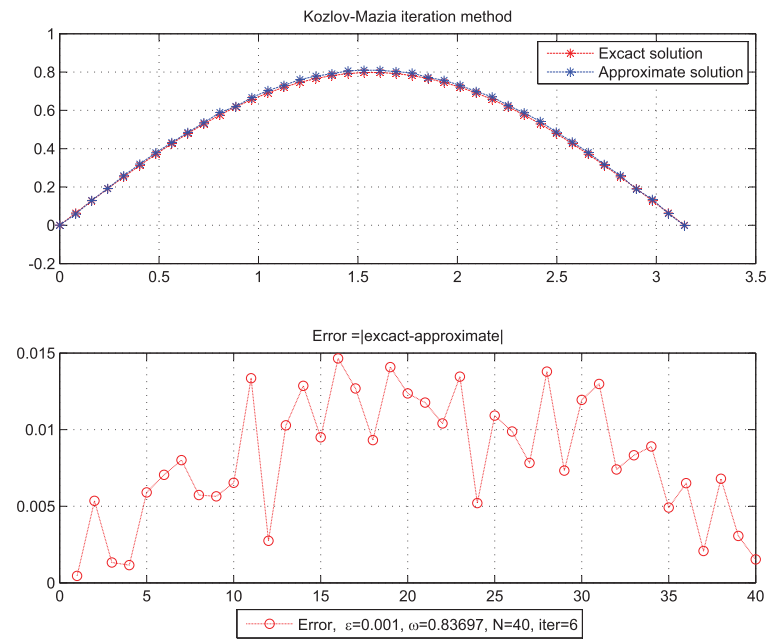


Figure 4 Noise level = 1/1,000, iter = 6.

Table 1 Kozlov-Maz'ya method

N	k	ϵ	ω	$E_r(f)$
40	5	0.01	0.83697	0.0523
40	6	0.01	0.83697	0.0612
40	5	0.001	0.83697	0.0054
40	6	0.001	0.83697	0.0162

Relative error $E_r(f)$.

6 Conclusion

The numerical results (Figures 1-4, Table 1) are quite satisfactory. Even with the noise level $\epsilon = 0.01$, the numerical solutions are still in good agreement with the exact solution.

In this study, a convergent and stable reconstruction of an unknown initial condition has been obtained using the Kozlov-Maz'ya iteration method. Both theoretical and numerical studies have been provided.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

All authors read and approved the final manuscript.

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